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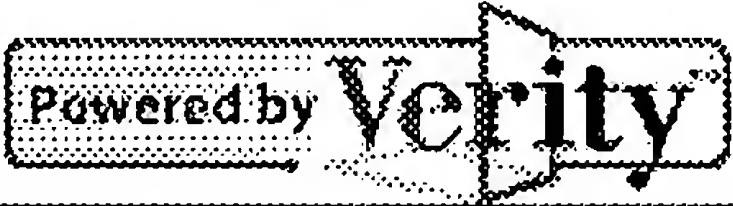   Full Text: PDF (344 kB)   GZipped PS   Order   Permissions for Reuse

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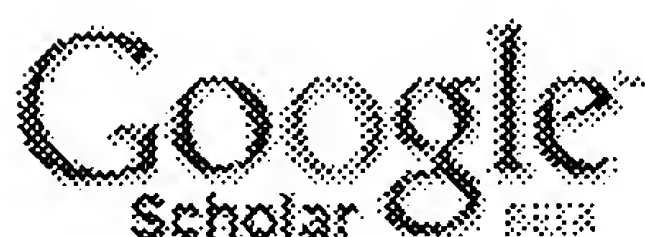
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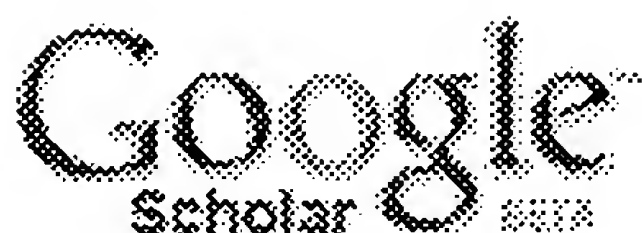synchROnization) system which is a distributed design negotiation ...
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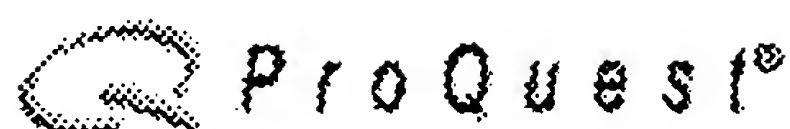
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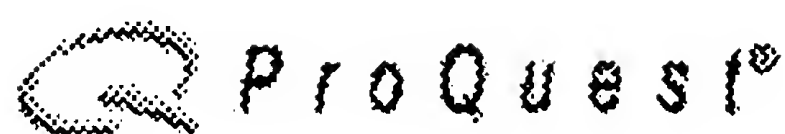
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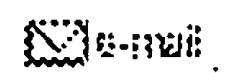
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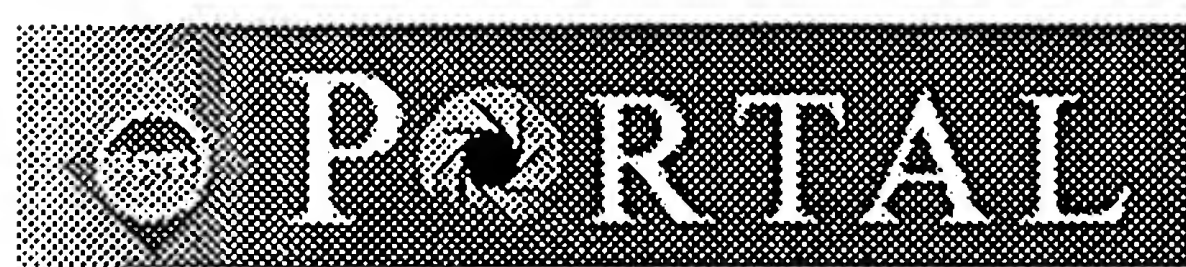
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Roman van der Krogt, Nico Roos, Mathijs de Weerdt, Cees Witteveen
July 2005 **Proceedings of the fourth international joint conference on Autonomous agents and multiagent systems AAMAS '05**
Publisher: ACM Press
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We present a novel approach to multiagent planning for self-interested agents. The main idea behind our approach is that multiagent planning systems should be built upon (single-agent) *plan repair* systems. In our system agents can exchange goals and subgoals through an auction, using their own (planning) heuristics and utility functions to determine when to auction and what to bid. Some experimental results for a logistics domain show that this system can be used to support the coordinati ...

Keywords: multiagent planning

2 Buffer planning: Buffer allocation algorithm with consideration of routing congestion
Yuchun Ma, Xianlong Hong, Sheqin Dong, Song Chen, Yici Cai, Chung-Kuan Cheng, Jun Gu
January 2004 **Proceedings of the 2004 conference on Asia South Pacific design automation: electronic design and solution fair ASP-DAC '04 ,**
Proceedings of the 2004 conference on Asia South Pacific design automation: electronic design and solution fair ASP-DAC '04
Publisher: IEEE Press , IEEE Press
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The dominating contribution of interconnect to system performance has made it critical to plan the buffers and the routes resource in the early stage of the layout. In this paper, we present a congestion estimation model which takes the buffer insertion sites into consideration. Based on the feasible region of the buffer insertion, the two-level tile structure is used to represent the distribution of the feasible buffer insertion sites among the routing tiles. And the buffer allocation method is ...

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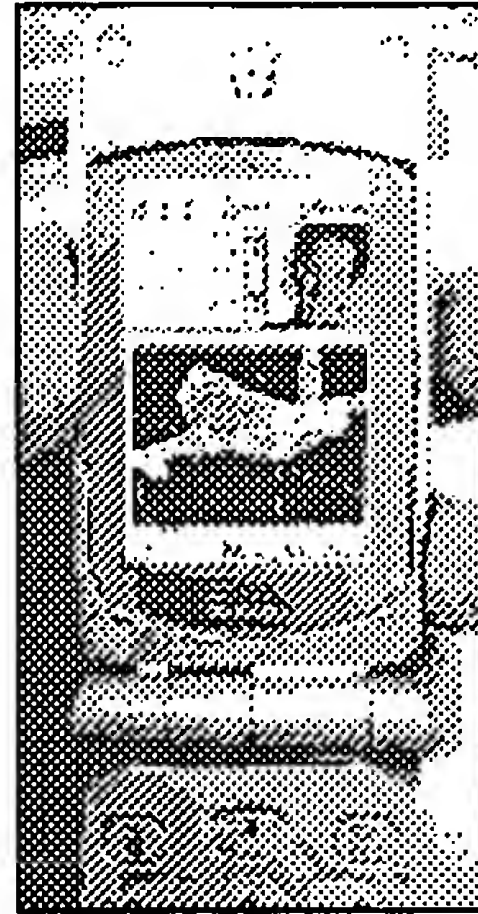
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Patent Applications

CAIRO
Application Number 60/127,672 filed March 31, 2000 for Collaborativ‹ Control And Synchronization System

DPM
DPM model and system for Dynamic Project Management. Disclosur Patent application is in progress.

MICE
MICE system for Mobile Interactive Collaboration Environment. Discl‹ TLO. Patent application is in progress.

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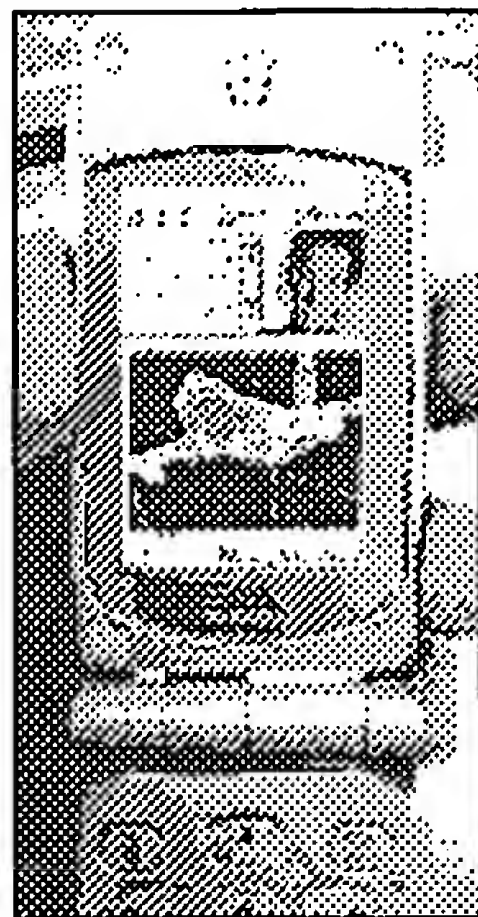
Patents

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Provisional Patent filed April 26, 2001 for Mechanisms and Ar Heterogeneous Platform Interfaces in a Collaboration (MIT Case Nc Crowley & Mofford, LLP file MIT-093PUSP)

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Provisional Patent to filed June 14, 2001 for Reliability Buffering(MI and Daly, Crowley & Mofford, LLP file MIT-086PUSP)

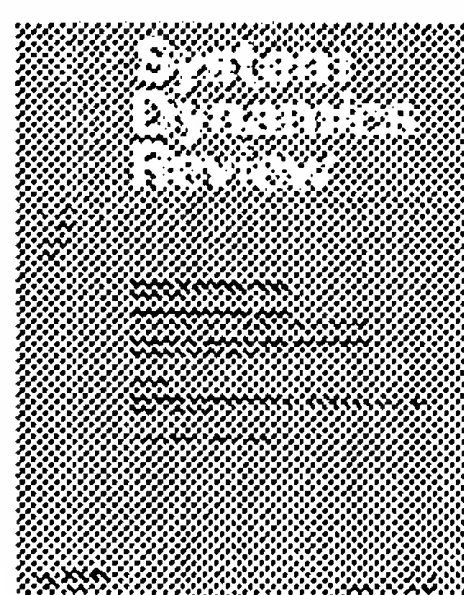# Dynamic Planning & Control Methodology

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Research Article
Dynamic change management for construction: introducing the change cycle into model-based project management

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ABSTRACT

In construction, rework (redoing previously completed work) has a considerable impact on pro-ject performance. As a result, construction managers often avoid rework on problematic tasks by modifying the design and specification of downstream tasks ("change"). Such a managerial action, however, can disturb the construction sequence by triggering non-value-adding change iterations among construction processes, which often contributes to unanticipated schedule delays and cost overruns. In order to address this challenging issue, different characteristics and behavior patterns of construction changes are identified, and compared to those of construction rework. Change impact on project performance is analyzed according to change characteristics, and to discovery status and time. All research findings are then incorporated into a cohesive dynamic project model. An application example of the project model demonstrates how model-based change management can enhance project performance in a real-world setting by providing effective management plans and policy guidelines. Finally, it is concluded that the model-based approach can be more effective, when combined with other managerial efforts such as reducing the process time and increasing the level of coordination among project functions. Copyright © 2003 John Wiley & Sons, Ltd.

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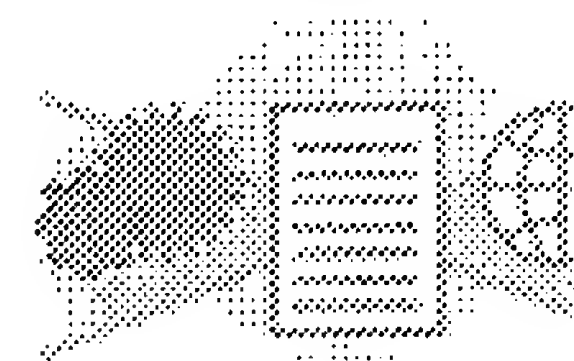- Find articles in Wiley InterScience written by any of the <u>authors</u>

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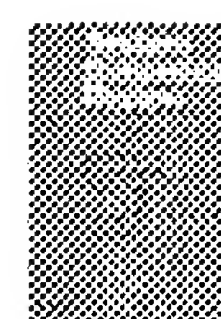
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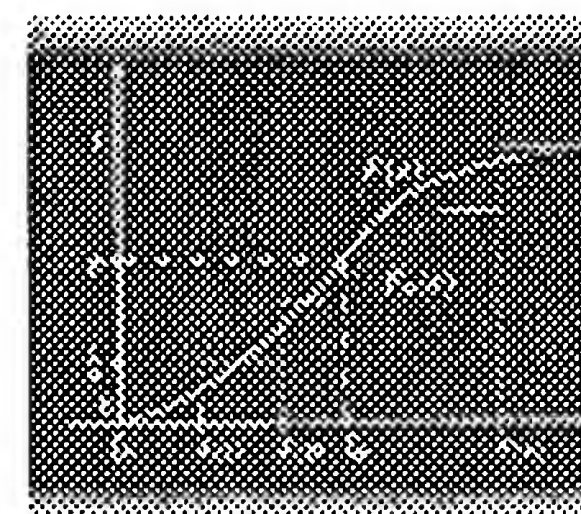
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